

Absolute Maximum Ratings (T_A = +25°C)

Supply Voltage (V+ to V-)	11V
Input Voltage	V- -0.5V, V+ +0.5V
Supply Turn-on Slew Rate	1V/μs
Digital & Analog Input Current (Note 1)	50mA
Output Current (Continuous)	50mA
ESD Rating	
Human Body Model (Per MIL-STD-883 Method 3015.7)	2500V
Machine Model	300V

Thermal Information

Storage Temperature Range	-65°C to +150°C
Ambient Operating Temperature	-40°C to +85°C
Operating Junction Temperature	-40°C to +125°C
Power Dissipation	See Curves
Pb-Free Reflow Profile	see link below
	http://www.intersil.com/pbfree/Pb-FreeReflow.asp

CAUTION: Do not operate at or near the maximum ratings listed for extended periods of time. Exposure to such conditions may adversely impact product reliability and result in failures not covered by warranty.

NOTE:

1. If an input signal is applied before the supplies are powered up, the input current must be limited to these maximum values.

IMPORTANT NOTE: All parameters having Min/Max specifications are guaranteed. Typical values are for information purposes only. Unless otherwise noted, all tests are at the specified temperature and are pulsed tests, therefore: T_J = T_C = T_A

Electrical Specifications V+ = +5V, V- = -5V, GND = 0V, T_A = +25°C, V_{OUT} = ±2V_{P-P} and R_L = 500Ω to GND, C_L = 0pF, unless otherwise specified.

PARAMETER	DESCRIPTION	CONDITIONS	MIN	TYP	MAX	UNIT
GENERAL						
+I _S Enabled	Enabled Supply Current	No load, V _{IN} = 0V, $\overline{\text{Enable}}$ Low	40	44	48	mA
-I _S Enabled	Enabled Supply Current	No load, V _{IN} = 0V, $\overline{\text{Enable}}$ Low	-45	-41	-37	mA
+I _S Disabled	Disabled Supply Current	No load, V _{IN} = 0V, $\overline{\text{Enable}}$ High	3	3.4	3.8	mA
-I _S Disabled	Disabled Supply Current	No load, V _{IN} = 0V, $\overline{\text{Enable}}$ High	-40	-6		μA
V _{OUT}	Positive and Negative Output Swing	V _{IN} = ±2.5V; R _L = 500Ω	±3.8	±4.0	±4.2	V
I _{OUT}	Output Current	V _{IN} = 0.825V R _L = 10Ω	±80	±135	±180	mA
V _{OS}	Output Offset Voltage		-40	-25	-10	mV
I _b	Input Bias Current	V _{IN} = 0V	-4	-2	-1	μA
R _{OUT}	HIZ Output Resistance	HIZ = Logic High	700	900	1150	Ω
R _{OUT}	Enabled Output Resistance	HIZ = Logic Low		0.2		Ω
R _{IN}	Input Resistance	V _{IN} = ±1.75V		10		MΩ
A _{CL} or A _V	Voltage Gain	R _L = 500Ω	1.94	1.99	2.04	V/V
LOGIC						
V _{IH}	Input High Voltage (Logic Inputs)			2		V
V _{IL}	Input Low Voltage (Logic Inputs)			0.8		V
I _{IH}	Input High Current (Logic Inputs)	V _H = 5V	200	260	320	μA
I _{IL}	Input Low Current (Logic Inputs)	V _L = 0V	-4	-2	-1	μA
AC GENERAL						
PSRR	Power Supply Rejection Ratio	DC, PSRR V+ and V- combined V _{OUT} = 0dBm	45	53		dB
Xtalk	Channel to Channel Crosstalk	f = 10MHz, ChX-Ch Y-Talk V _{IN} = 1V _{P-P} ; C _L = 1.1pF		74		dB
Off - ISO	Off-State Isolation	f = 10MHz, Ch-Ch Off Isolation V _{IN} = 1V _{P-P} ; C _L = 1.1pF		76		dB
dG	Differential Gain Error	NTC-7, R _L = 150, C _L = 1.1pF		0.008		%
dP	Differential Phase Error	NTC-7, R _L = 150, C _L = 1.1pF		0.01		°

ISL59446

Electrical Specifications $V_+ = +5V$, $V_- = -5V$, $GND = 0V$, $T_A = +25^\circ C$, $V_{OUT} = \pm 2V_{P-P}$ and $R_L = 500\Omega$ to GND , $C_L = 0pF$, unless otherwise specified. **(Continued)**

PARAMETER	DESCRIPTION	CONDITIONS	MIN	TYP	MAX	UNIT
BW	Small Signal -3dB Bandwidth	$V_{OUT} = 0.2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		620		MHz
		$V_{OUT} = 0.2V_{P-P}$; $R_L = 150\Omega$, $C_L = 2.1pF$		530		MHz
	Large Signal -3dB Bandwidth	$V_{OUT} = 2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		280		MHz
		$V_{OUT} = 2V_{P-P}$; $R_L = 150\Omega$, $C_L = 1.1pF$		260		MHz
FBW	0.1dB Bandwidth	$V_{OUT} = 2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		160		MHz
		$V_{OUT} = 2V_{P-P}$; $R_L = 150\Omega$, $C_L = 1.1pF$		50		MHz
SR	Slew Rate	25% to 75%, $R_L = 150\Omega$, Input Enabled, $C_L = 2.1pF$		1600		V/ μs
TRANSIENT RESPONSE						
tr, tf Large Signal	Large Signal Rise, Fall Times, tr, tf, 10% - 90%	$V_{OUT} = 2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		1.2		ns
		$V_{OUT} = 2V_{P-P}$; $R_L = 150\Omega$, $C_L = 2.1pF$		1.3		ns
tr, tf, Small Signal	Small Signal Rise, Fall Times, tr, tf, 10% - 90%	$V_{OUT} = 0.2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		0.7		ns
		$V_{OUT} = 0.2V_{P-P}$; $R_L = 150\Omega$, $C_L = 2.1pF$		0.9		ns
ts 0.1%	Settling Time to 0.1%	$V_{OUT} = 2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		7.2		ns
		$V_{OUT} = 2V_{P-P}$; $R_L = 150\Omega$, $C_L = 2.1pF$		8.2		ns
ts 1%	Settling Time to 1%	$V_{OUT} = 2V_{P-P}$; $R_L = 500\Omega$, $C_L = 1.1pF$		4		ns
		$V_{OUT} = 2V_{P-P}$; $R_L = 150\Omega$, $C_L = 2.1pF$		4.3		ns
SWITCHING CHARACTERISTICS						
V_{GLITCH}	Channel - to- Channel Switching Glitch	$V_{IN} = 0V$, $R_L = 500\Omega$; $C_L = 1.1pF$		90		mV _{P-P}
		$V_{IN} = 0V$, $R_L = 150\Omega$; $C_L = 2.1pF$		15		mV _{P-P}
	Enable Switching Glitch	$V_{IN} = 0V$, $R_L = 500\Omega$; $C_L = 1.1pF$		1.8		V _{P-P}
		$V_{IN} = 0V$, $R_L = 150\Omega$; $C_L = 2.1pF$		1.35		V _{P-P}
	HIZ Switching Glitch	$V_{IN} = 0V$, $R_L = 500\Omega$; $C_L = 1.1pF$		340		mV _{P-P}
		$V_{IN} = 0V$, $R_L = 150\Omega$; $C_L = 2.1pF$		340		mV _{P-P}
t_{SW-L-H}	Channel Switching Time Low to High	1.2V logic threshold to 10% movement of analog output		24		ns
t_{SW-H-L}	Channel Switching Time High to Low	1.2V logic threshold to 10% movement of analog output		24		ns
tpd	Propagation Delay	10% to 10%		0.55		ns

Typical Performance Curves $V_S = \pm 5V$, $R_L = 500\Omega$ to GND, $T_A = +25^\circ C$, unless otherwise specified.

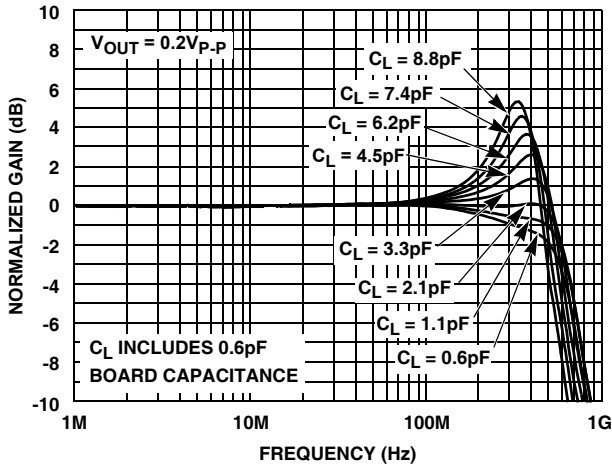


FIGURE 1. SMALL SIGNAL GAIN vs FREQUENCY vs C_L INTO 500Ω LOAD

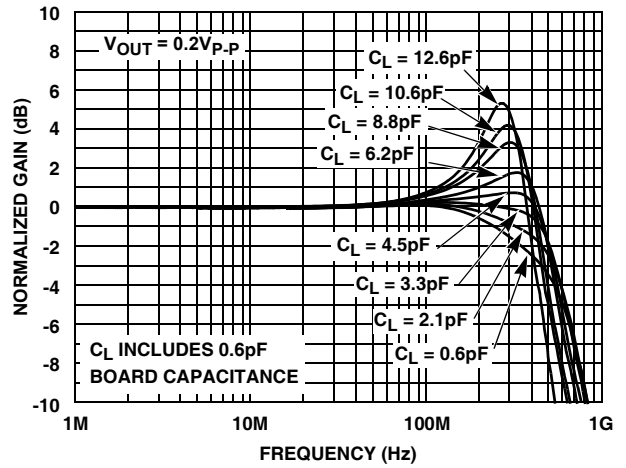


FIGURE 2. SMALL SIGNAL GAIN vs FREQUENCY vs C_L INTO 150Ω LOAD

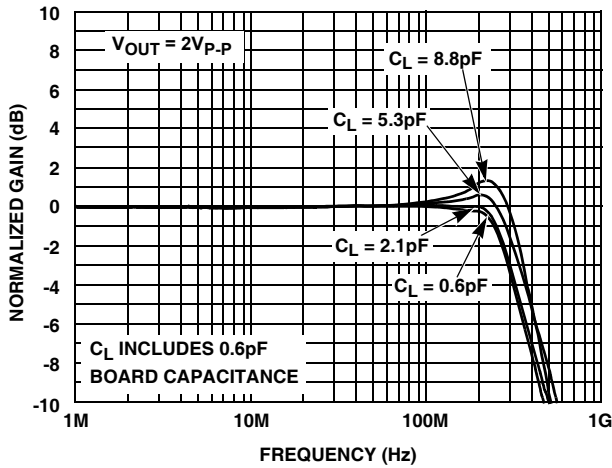


FIGURE 3. LARGE SIGNAL GAIN vs FREQUENCY vs C_L INTO 500Ω LOAD

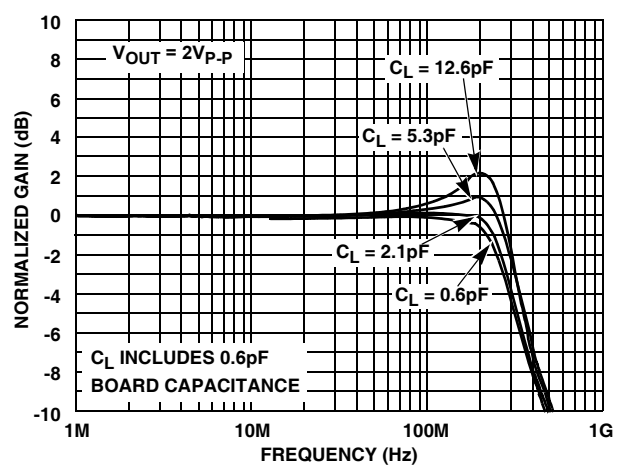


FIGURE 4. LARGE SIGNAL GAIN vs FREQUENCY vs C_L INTO 150Ω LOAD

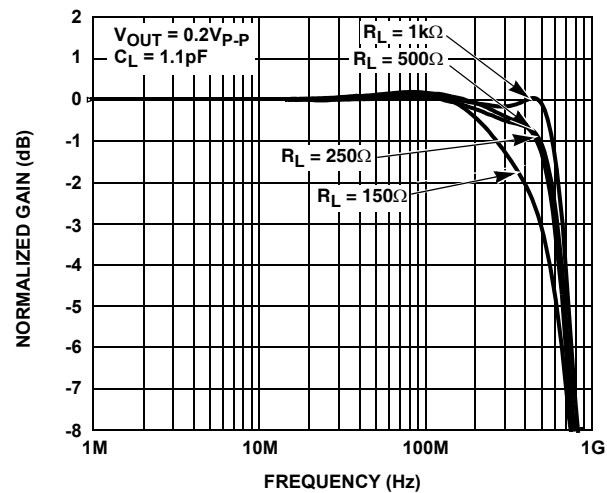


FIGURE 5. GAIN vs FREQUENCY vs R_L

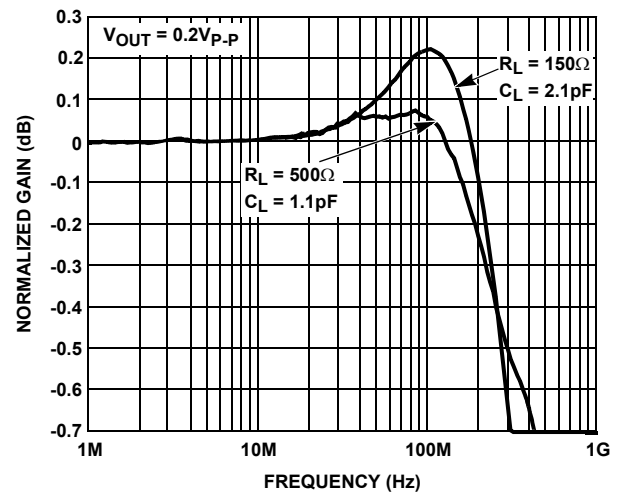


FIGURE 6. 0.1dB GAIN FLATNESS

Typical Performance Curves $V_S = \pm 5V$, $R_L = 500\Omega$ to GND, $T_A = +25^\circ C$, unless otherwise specified. (Continued)

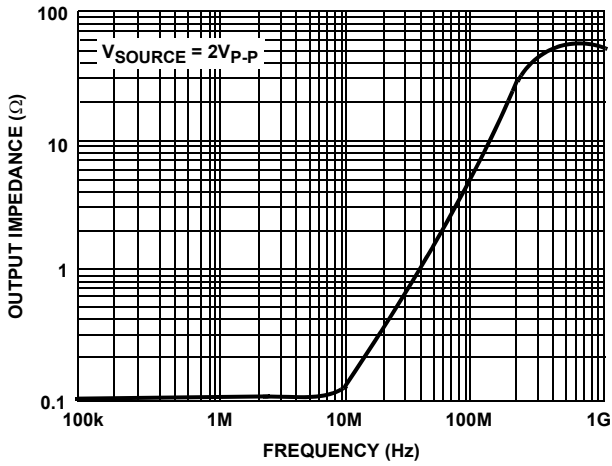


FIGURE 7. Z_{OUT} vs FREQUENCY - ENABLED

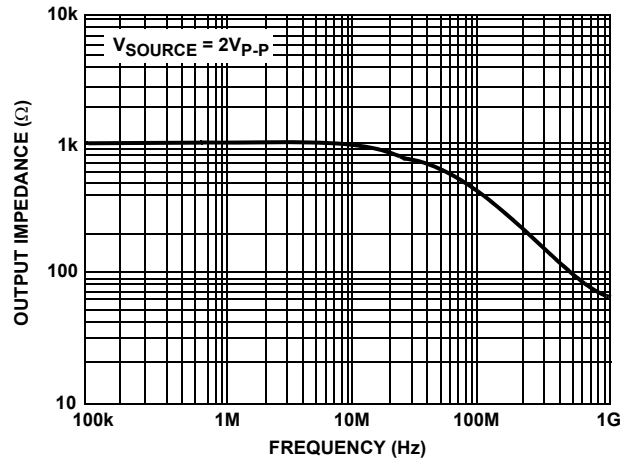


FIGURE 8. Z_{OUT} vs FREQUENCY - HIZ

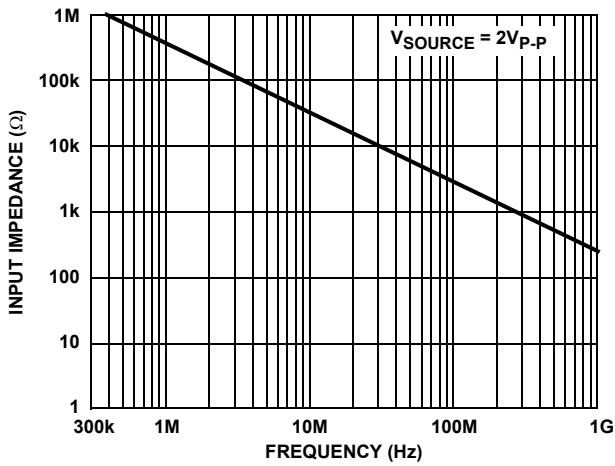


FIGURE 9. Z_{IN} vs FREQUENCY

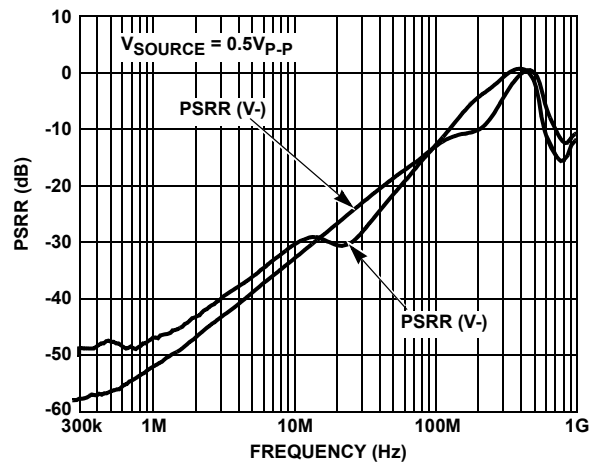


FIGURE 10. PSRR vs FREQUENCY

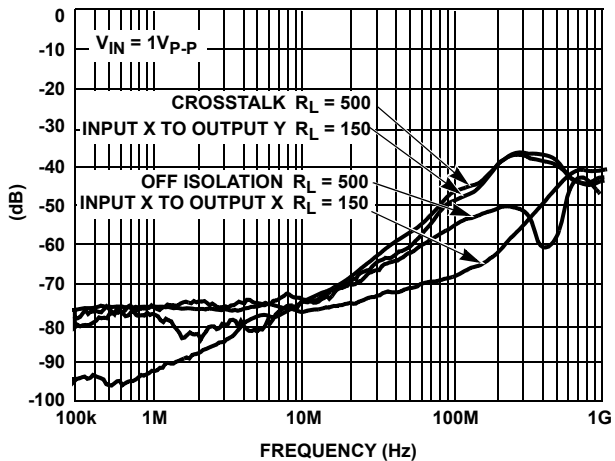


FIGURE 11. Crosstalk and Off Isolation

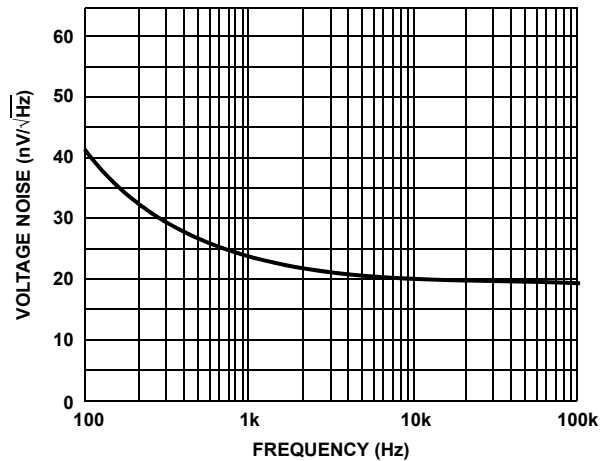


FIGURE 12. Input Noise vs Frequency

Typical Performance Curves $V_S = \pm 5V$, $R_L = 500\Omega$ to GND, $T_A = +25^\circ C$, unless otherwise specified. (Continued)

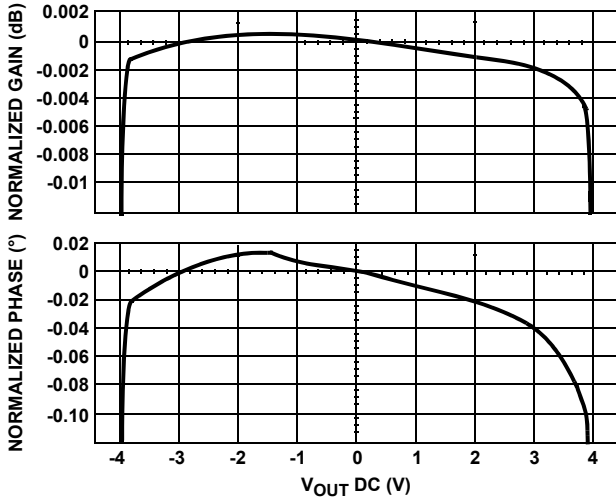


FIGURE 13. DIFFERENTIAL GAIN AND PHASE;
 $V_{OUT} = 0.2V_{P-P}$, $F_O = 3.58MHz$, $R_L = 500\Omega$

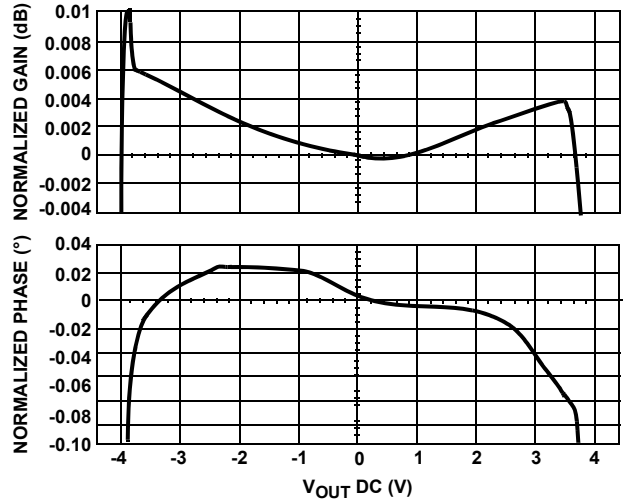


FIGURE 14. DIFFERENTIAL GAIN AND PHASE;
 $V_{OUT} = 0.2V_{P-P}$, $F_O = 3.58MHz$, $R_L = 150\Omega$

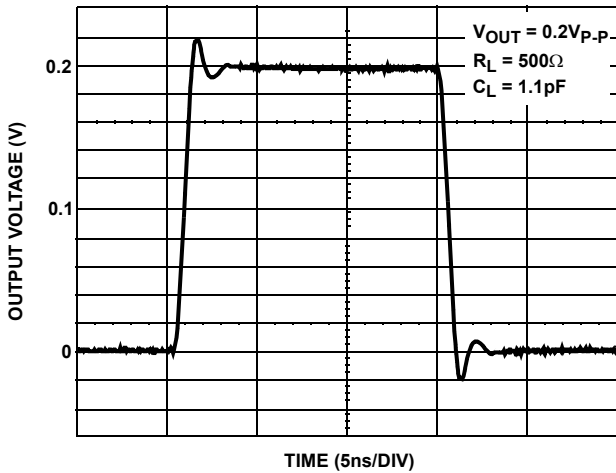


FIGURE 15. SMALL SIGNAL TRANSIENT RESPONSE;
 $R_L = 500\Omega$

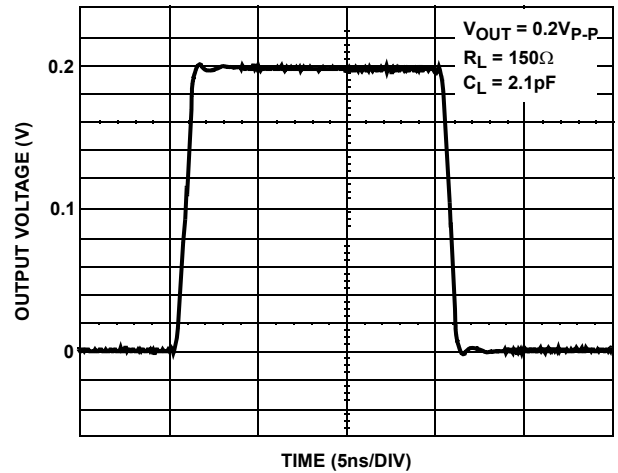


FIGURE 16. SMALL SIGNAL TRANSIENT RESPONSE;
 $R_L = 150\Omega$

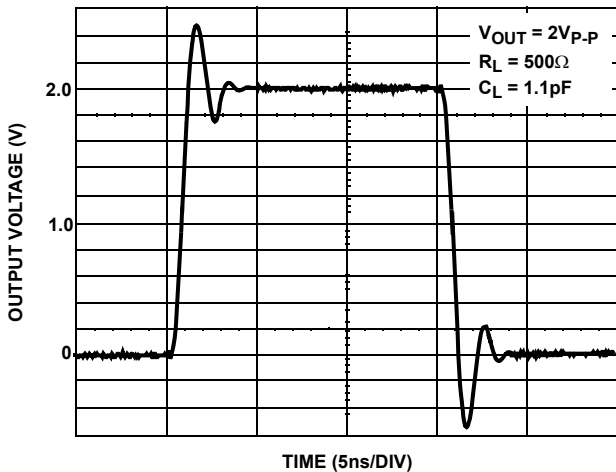


FIGURE 17. LARGE SIGNAL TRANSIENT RESPONSE;
 $R_L = 500\Omega$

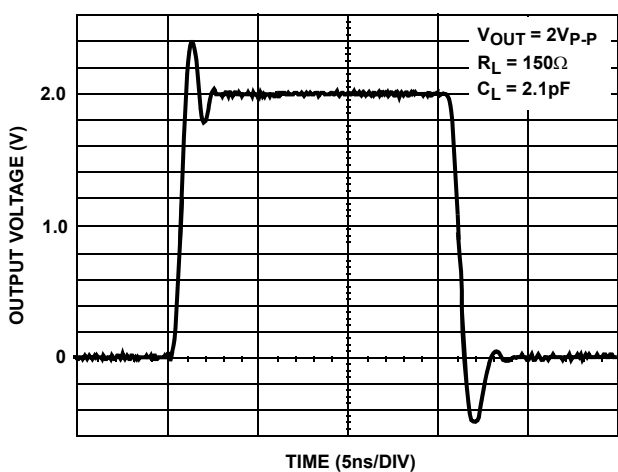


FIGURE 18. LARGE SIGNAL TRANSIENT RESPONSE;
 $R_L = 150\Omega$

Typical Performance Curves $V_S = \pm 5V$, $R_L = 500\Omega$ to GND, $T_A = +25^\circ C$, unless otherwise specified. (Continued)

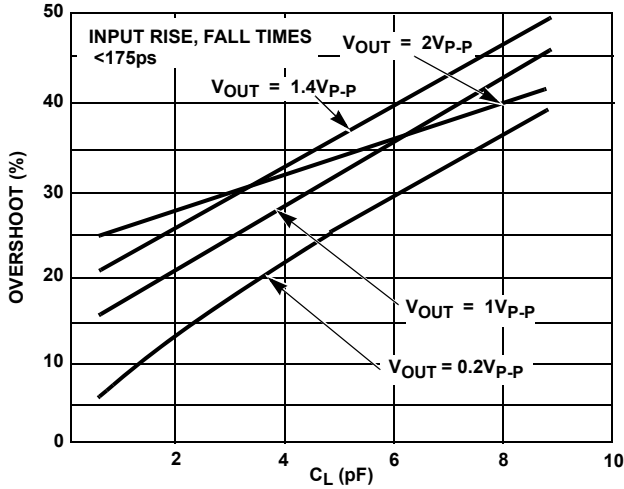


FIGURE 19. PULSE OVERSHOOT vs V_{OUT} , C_L ; $R_L = 500\Omega$

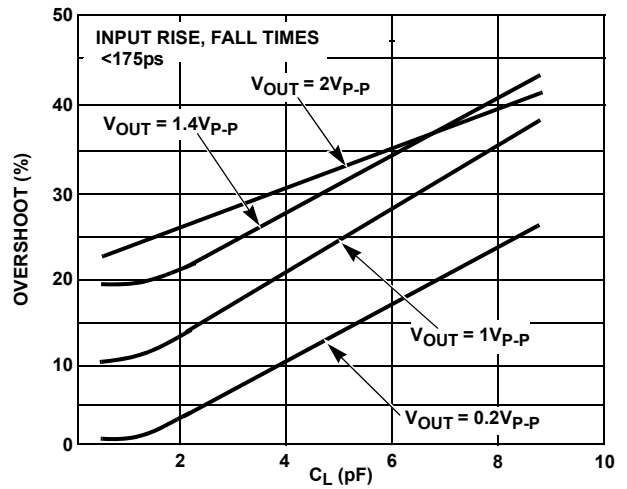


FIGURE 20. PULSE OVERSHOOT vs V_{OUT} , C_L ; $R_L = 150\Omega$

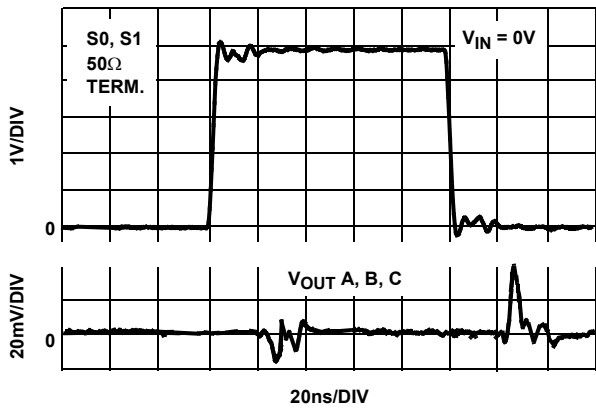


FIGURE 21. CHANNEL TO CHANNEL SWITCHING GLITCH $V_{IN} = 0V$

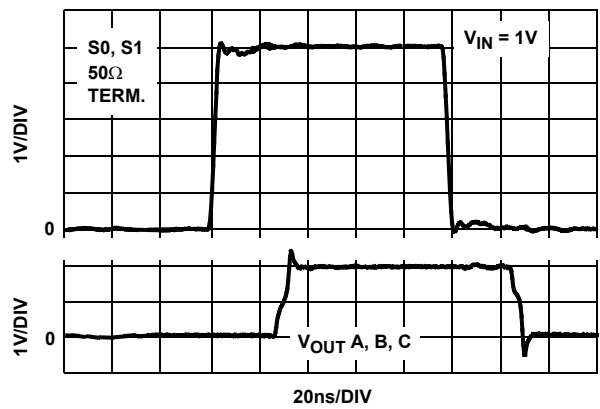


FIGURE 22. CHANNEL TO CHANNEL TRANSIENT RESPONSE $V_{IN} = 1V$

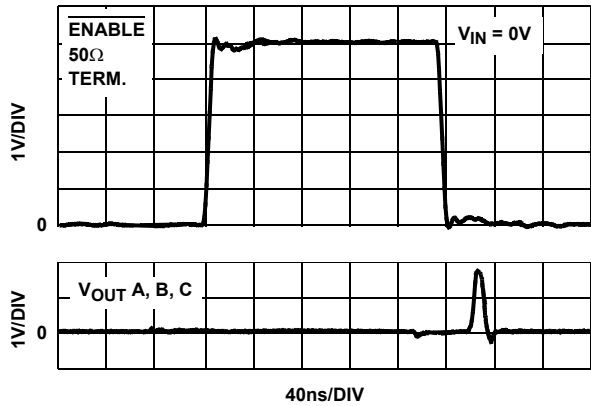


FIGURE 23. ENABLE SWITCHING GLITCH $V_{IN} = 0V$

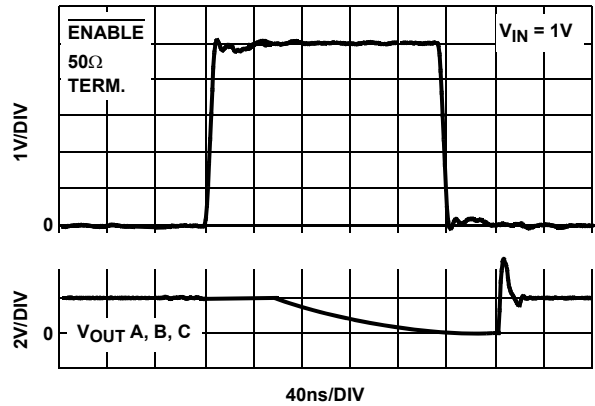


FIGURE 24. ENABLE TRANSIENT RESPONSE $V_{IN} = 1V$

Typical Performance Curves $V_S = \pm 5V$, $R_L = 500\Omega$ to GND, $T_A = +25^\circ C$, unless otherwise specified. (Continued)

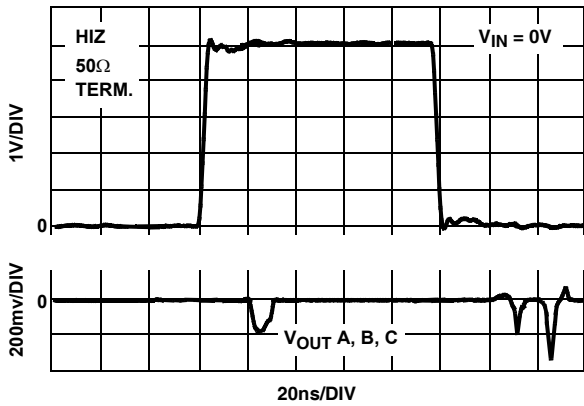


FIGURE 25. HIZ SWITCHING GLITCH $V_{IN} = 0V$

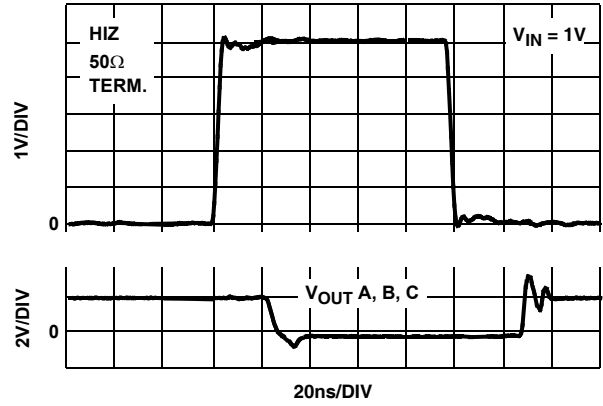


FIGURE 26. HIZ TRANSIENT RESPONSE $V_{IN} = 1V$

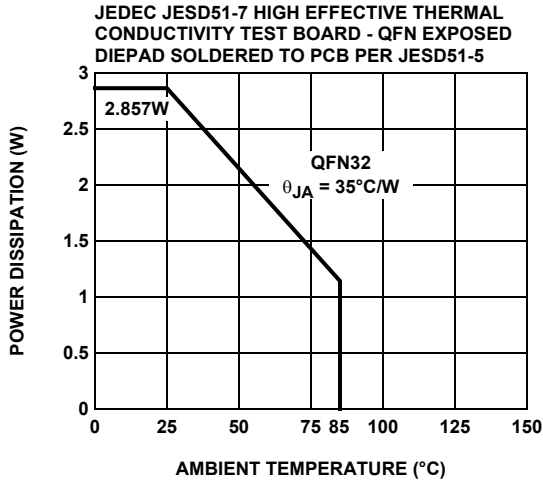


FIGURE 27. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

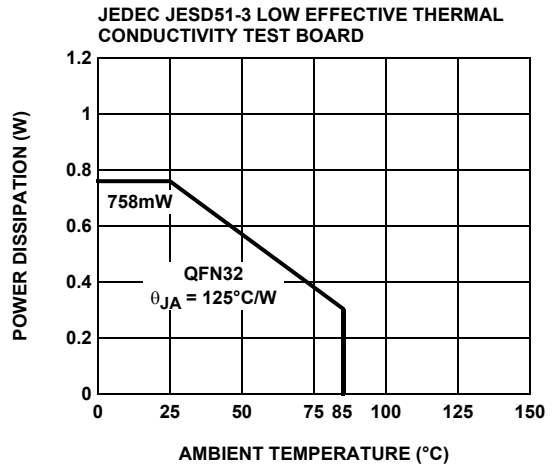
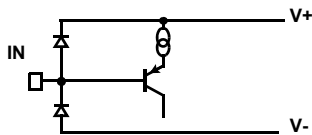


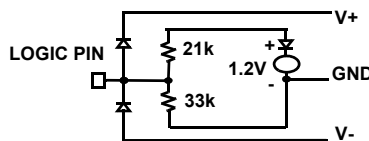
FIGURE 28. PACKAGE POWER DISSIPATION vs AMBIENT TEMPERATURE

Pin Descriptions

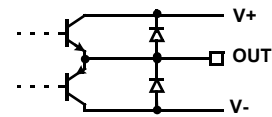
ISL59446 (32 LD QFN)	PIN NAME	EQUIVALENT CIRCUIT	DESCRIPTION
1	IN1A	Circuit 1	Channel 1 input for output amplifier "A"
2, 4, 8, 13, 15, 24, 28, 30	NIC		Not Internally Connected; it is recommended these pins be tied to ground to minimize crosstalk.
3	IN1B	Circuit 1	Channel 1 input for output amplifier "B"
5	IN1C	Circuit 1	Channel 1 input for output amplifier "C"
6	GNDB	Circuit 4	Ground pin for output amplifier "B"
7	IN2A	Circuit 1	Channel 2 input for output amplifier "A"
9	IN2B	Circuit 1	Channel 2 input for output amplifier "B"
10	IN2C	Circuit 1	Channel 2 input for output amplifier "C"
11	GNDC	Circuit 4	Ground pin for output amplifier "C"
12	IN3A	Circuit 1	Channel 3 input for output amplifier "A"
14	IN3B	Circuit 1	Channel 3 input for output amplifier "B"
16	IN3C	Circuit 1	Channel 3 input for output amplifier "C"
17	S1	Circuit 2	Channel selection pin MSB (binary logic code)
18	S0	Circuit 2	Channel selection pin. LSB (binary logic code)
19	OUTC	Circuit 3	Output of amplifier "C"
20	OUTB	Circuit 3	Output of amplifier "B"
21	V-	Circuit 4	Negative power supply
22	OUTA	Circuit 3	Output of amplifier "A"
23	V+	Circuit 4	Positive power supply
25	ENABLE	Circuit 2	Device enable (active low). Internal pull-down resistor ensures device is active with no connection to this pin. A logic High puts device into power-down mode and only the logic circuitry is active. Logic states are preserved post power-down.
26	HIZ	Circuit 2	Output disable (active high). Internal pull-down resistor ensures the device will be active with no connection to this pin. A logic high, puts the outputs in a high impedance state. Use this state to control logic when more than one MUX-amp share the same video output line.
27	IN0C	Circuit 1	Channel 0 for output amplifier "C"
29	IN0B	Circuit 1	Channel 0 for output amplifier "B"
31	IN0A	Circuit 1	Channel 0 for output amplifier "A"
32	GNDA	Circuit 4	Ground pin for output amplifier "A"



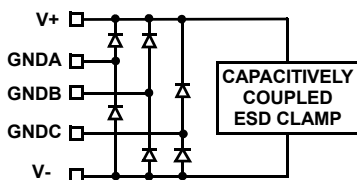
CIRCUIT 1



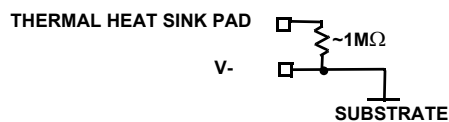
CIRCUIT 2



CIRCUIT 3



CIRCUIT 4



AC Test Circuits

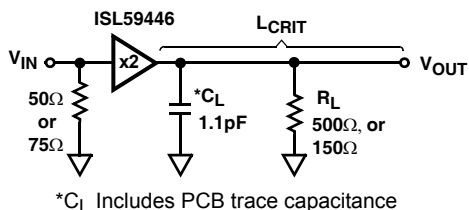


FIGURE 29A. TEST CIRCUIT WITH OPTIMAL OUTPUT LOAD

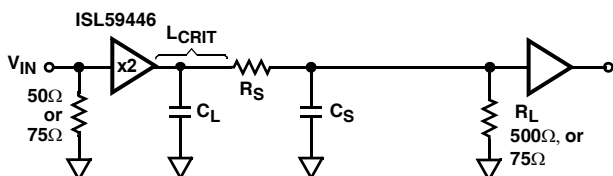


FIGURE 29B. INTER-STAGE APPLICATION CIRCUIT

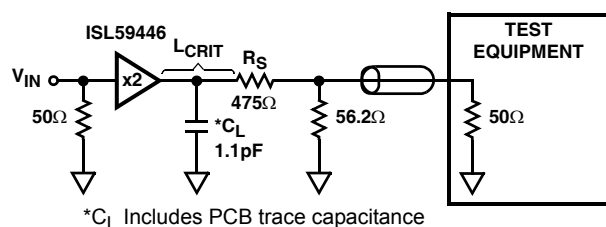


FIGURE 29C. 500Ω TEST CIRCUIT WITH 50Ω LOAD

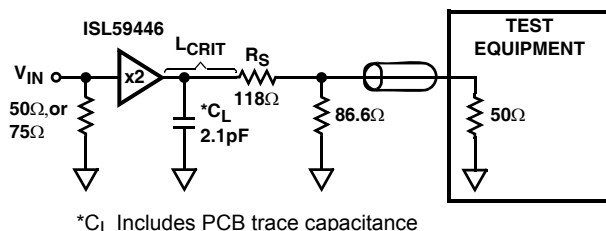


FIGURE 29D. 150Ω TEST CIRCUIT WITH 50Ω LOAD

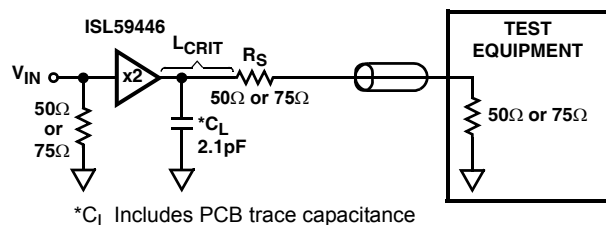


FIGURE 29E. BACKLOADED TEST CIRCUIT FOR 75Ω VIDEO CABLE APPLICATION

AC Test Circuits

Figures 29C and 29D illustrate the optimum output load for testing AC performance at 500Ω and 150Ω loads.

Figure 29E illustrates the optimum output load for 50Ω and 75Ω cable-driving.

Application Information

General

Key features of the ISL59446 include a fixed gain of 2, buffered high impedance analog inputs and excellent AC performance at output loads down to 150Ω for video cable-driving. The current feedback output amplifiers are stable operating into capacitive loads.

For the best isolation and crosstalk rejection, all GND pins and NIC pins must connect to the GND plane.

AC Design Considerations

High speed current-feed amplifiers are sensitive to capacitance at the inverting input and output terminals. The ISL59446 has an internally set gain of 2, so the inverting input is not accessible. Capacitance at the output terminal increases gain peaking (Figure 1) and pulse overshoot (Figures 19 and 20). The AC response of the ISL59446 is optimized for a total output capacitance of up to 2.1pF over the load range of 150Ω to 500Ω. When PCB trace capacitance and component capacitance exceed 2pF, pulse overshoot becomes strongly dependent on the input pulse amplitude and slew rate. This effect is shown in Figures 19 and 20, which show approximate pulse overshoot as a function of input slew rate and output capacitance. Fast pulse rise and fall times (<150ns) at input amplitudes above 0.2V, cause the input pulse slew rate to exceed the 1600V/μs output slew rate of the ISL59446. At 125ps rise time, pulse input amplitudes >0.2V cause slew rate limit operation. Increasing levels of output capacitance reduce stability resulting in increased overshoot, and settling time.

PC board trace length should be kept to a minimum in order to minimize output capacitance and prevent the need for controlled impedance lines. At 500MHz trace lengths approaching 1" begin exhibiting transmission line behavior and may cause excessive ringing if controlled impedance traces are not used. Figure 29A shows the optimum inter-stage circuit when the total output trace length is less than the critical length of the highest signal frequency.

For applications where pulse response is critical and where inter-stage distances exceed L_{CRIT} , the circuit shown in Figure 29B is recommended. Resistor R_S constrains the capacitance seen by the amplifier output to the trace capacitance from the output pin to the resistor. Therefore, R_S should be placed as close to the ISL59446 output pin as possible. For inter-stage distances much greater than L_{CRIT} , the back-loaded circuit shown in Figure 29E should be used with controlled impedance PCB lines, with R_S and R_L equal to the controlled impedance.

For applications where inter-stage distances are long, but pulse response is not critical, capacitor C_S can be added to low values of R_S to form a low-pass filter to dampen pulse overshoot. This approach avoids the need for the large gain correction required by the -6dB attenuation of the

back-loaded controlled impedance interconnect. Load resistor R_L is still required but can be 500Ω or greater, resulting in a much smaller attenuation factor.

Control Signals

S_0 , S_1 , $\overline{\text{ENABLE}}$, HIZ - These are binary coded, TTL/CMOS compatible control inputs. The S_0 , S_1 pins select the inputs. All three amplifiers are switched simultaneously from their respective inputs. The $\overline{\text{ENABLE}}$ pin is used to disable the part to save power, and the HIZ pin to set the output stage in a high impedance state. For control signal rise and fall times less than 10ns the use of termination resistors close to the part may be necessary to prevent reflections and to minimize transients coupled to the output.

Power-Up Considerations

The ESD protection circuits use internal diodes from all pins to the $V+$ and $V-$ supplies. In addition, a dV/dT -triggered clamp is connected between the $V+$ and $V-$ pins, as shown in the Equivalent Circuits 1 through 4 section of the Pin Description table. The dV/dT triggered clamp imposes a maximum supply turn-on slew rate of $1V/\mu\text{s}$. Damaging currents can flow for power supply rates-of-rise in excess of $1V/\mu\text{s}$, such as during hot plugging. Under these conditions, additional methods should be employed to ensure the rate of rise is not exceeded.

Consideration must be given to the order in which power is applied to the $V+$ and $V-$ pins, as well as analog and logic input pins. Schottky diodes (Motorola MBR0550T or equivalent) connected from $V+$ to ground and $V-$ to ground (Figure 30) will shunt damaging currents away from the internal $V+$ and $V-$ ESD diodes in the event that the $V+$ supply is applied to the device before the $V-$ supply.

If positive voltages are applied to the logic or analog video input pins before $V+$ is applied, current will flow through the internal ESD diodes to the $V+$ pin. The presence of large decoupling capacitors and the loading effect of other circuits connected to $V+$, can result in damaging currents through the ESD diodes and other active circuits within the device. Therefore, adequate current limiting on the digital and analog inputs is needed to prevent damage during the time the voltages on these inputs are more positive than $V+$.

HIZ State

An internal pull-down resistor ensures the device will be active with no connection to the HIZ pin. The HIZ state is established within approximately 20ns (Figure 26) by placing a logic high ($>2V$) on the HIZ pin. If the HIZ state is selected, the output impedance is $\sim 1000\Omega$ (Figure 8). The supply current during this state is same as the active state.

ENABLE and Power-Down States

The enable pin is active low. An internal pull-down resistor ensures the device will be active with no connection to the $\overline{\text{ENABLE}}$ pin. The power-down state is established within approximately 200ns (Figure 24), if a logic high ($>2V$) is placed on the $\overline{\text{ENABLE}}$ pin. In the power-down state, the output has no leakage but has a large variable capacitance (on the order of 15pF), and is capable of being back-driven. Under this condition, large incoming slew rates can cause fault currents of tens of mA. Therefore, the parallel connection of multiple outputs is not recommended unless the application can tolerate the limited power-down output impedance.

Limiting the Output Current

No output short circuit current limit exists on these parts. All applications need to limit the output current to less than 50mA. Adequate thermal heat sinking of the parts is also required.

PC Board Layout

The AC performance of this circuit depends greatly on the care taken in designing the PC board. The following are recommendations to achieve optimum high frequency performance from your PC board.

- The use of low inductance components such as chip resistors and chip capacitors is strongly recommended.
- Minimize signal trace lengths. Trace inductance and capacitance can easily limit circuit performance. Avoid sharp corners, use rounded corners when possible. Vias in the signal lines add inductance at high frequency and should be avoided. PCB traces greater than 1" begin to exhibit transmission line characteristics with signal rise/fall times of 1ns or less. High frequency performance may be degraded for traces greater than one inch, unless strip line are used.

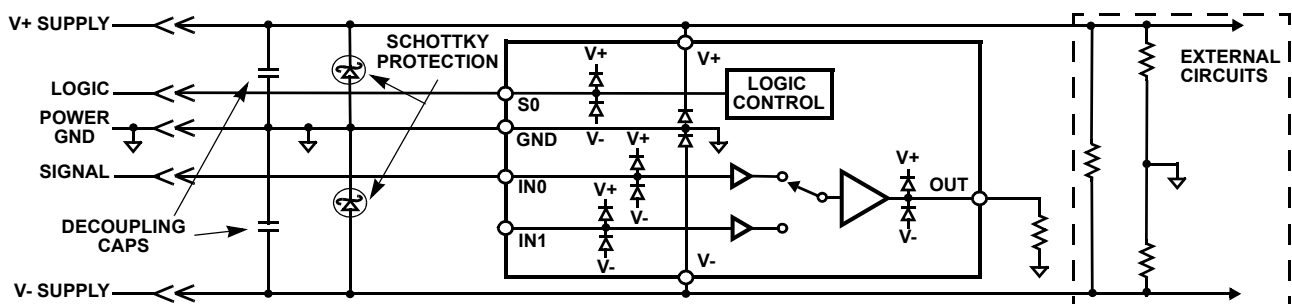


FIGURE 30. SCHOTTKY PROTECTION CIRCUIT

- Match Channel-Channel analog I/O trace lengths and layout symmetry. This will minimize propagation delay mismatches.
- Maximize use of AC decoupled PCB layers. All signal I/O lines should be routed over continuous ground planes (i.e. no split planes or PCB gaps under these lines). Avoid vias in the signal I/O lines.
- Use proper value and location of termination resistors. Termination resistors should be as close to the device as possible.
- When testing use good quality connectors and cables, matching cable types and keeping cable lengths to a minimum.
- Minimum of 2 power supply decoupling capacitors are recommended (1000pF, 0.01μF) as close to the devices as possible - avoid vias between the cap and the device because vias add unwanted inductance. Larger caps can be farther away. When vias are required in a layout, they should be routed as far away from the device as possible.
- The NIC pins are placed on both sides of the input pins. These pins are not internally connected to the die. It is recommended these pins be tied to ground to minimize crosstalk.

The QFN Package Requires Additional PCB Layout Rules for the Thermal Pad

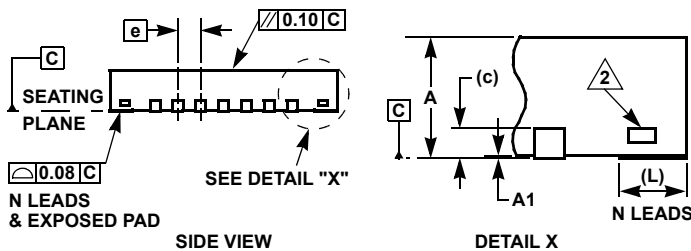
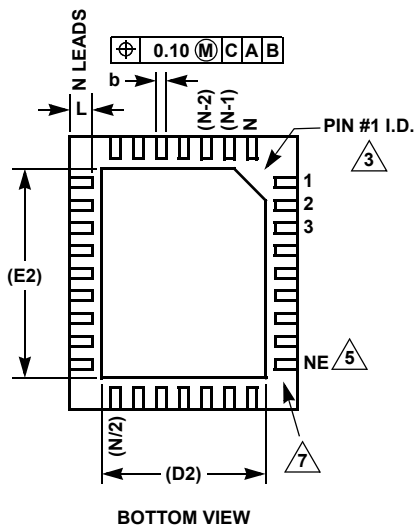
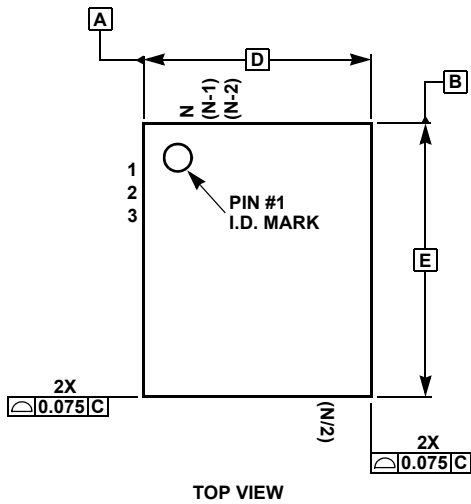
The thermal pad is electrically connected to V- supply through the high resistance IC substrate. Its primary function is to provide heat sinking for the IC. However, because of the connection to the V- supply through the substrate, the thermal pad must be tied to the V- supply to prevent unwanted current flow to the thermal pad. Do **not** tie this pin to GND as this could result in large back biased currents flowing between GND and V-. The ISL59446 the package with pad dimensions of D2 = 2.48mm and E2 = 3.4mm.

Maximum AC performance is achieved if the thermal pad is attached to a dedicated decoupled layer in a multi-layered PC board. In cases where a dedicated layer is not possible, AC performance may be reduced at upper frequencies.

- The thermal pad requirements are proportional to power dissipation and ambient temperature. A dedicated layer eliminates the need for individual thermal pad area. When a dedicated layer is not possible a 1" x 1" pad area is sufficient for the ISL59446 that is dissipating 0.5W in +50°C ambient. Pad area requirements should be evaluated on a case by case basis.

**Quad Flat No-Lead Plastic Package (QFN)
Micro Lead Frame Plastic Package (MLFP)**

L32.5x6A (One of 10 Packages in MDP0046)
32 LEAD QUAD FLAT NO-LEAD PLASTIC PACKAGE
(COMPLIANT TO JEDEC MO-220)



SYMBOL	MILLIMETERS			NOTES
	MIN	NOMINAL	MAX	
A	0.80	0.90	1.00	-
A1	0.00	0.02	0.05	-
D	5.00 BSC			-
D2	2.48 REF			-
E	6.00 BSC			-
E2	3.40 REF			-
L	0.45	0.50	0.55	-
b	0.17	0.22	0.27	-
c	0.20 REF			-
e	0.50 BSC			-
N	32 REF			4
ND	7 REF			6
NE	9 REF			5

Rev 1 2/09

NOTES:

1. Dimensioning and tolerancing per ASME Y14.5M-1994.
2. Tiebar view shown is a non-functional feature.
3. Bottom-side pin #1 I.D. is a diepad chamfer as shown.
4. N is the total number of terminals on the device.
5. NE is the number of terminals on the "E" side of the package (or Y-direction).
6. ND is the number of terminals on the "D" side of the package (or X-direction). ND = (N/2)-NE.
7. Inward end of terminal may be square or circular in shape with radius (b/2) as shown.

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